

## ***Slam2000 Handheld Handheld 3D Laser Scanner***

SLAM2000 is a high-precision handheld laser scanner. The device has a panoramic laser field of view, an integrated visual camera and texture camera, a replaceable lithium battery handle, a built-in high-precision inertial navigation unit and a high-performance computing unit to enable real-time 3D data acquisition and mapping.



SLAM2000 is a high-precision handheld laser scanner. The device has a panoramic laser field of view, an integrated visual camera and a texture camera, a replaceable lithium battery handle, a built-in high-precision inertial navigation unit, and a high-performance computing unit to enable real-time 3D data acquisition and mapping. SLAM2000 can be expanded to connect to a variety of external devices such as RTK, backpack, power supply, tripod, etc., and can be widely used in closed spaces, volumetric surveying, and mapping, emergency rescue, real-time navigation, and other scenarios.

### **Features:**

Panoramic laser FOV

High-precision surveying and mapping

Real-time mapping

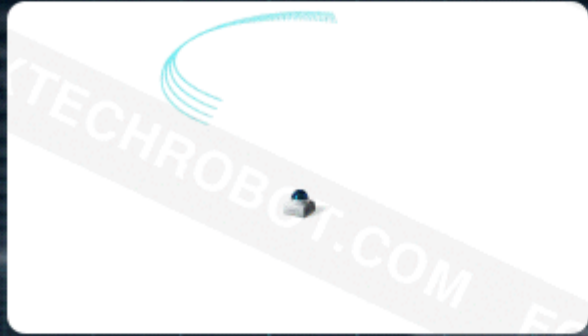
Visual camera

Texture camera

Abundant extension

## 360° Panoramic Laser FOV

Integrated with a 360-degree rotational head, the hemispherical non repetitive scanning laser can form a panoramic laser field of view, ensuring multi-directional and full-angle data collection. You can see when you walk, and you can get what you see.



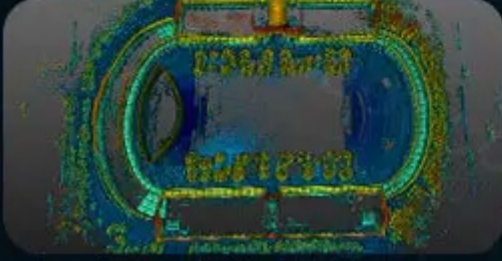
## High Precision Surveying and Real-time Mapping

The built-in high precision inertial navigation unit effectively reduces accumulated errors. The high precision calibration algorithm further improves the accuracy of the laser sensor. Also, the professional SLAM algorithm achieves high precision mapping results.



## Visual Camera

- 12-megapixel visual camera
- Visual SLAM algorithms
- Obtain high-definition images of local scenes.

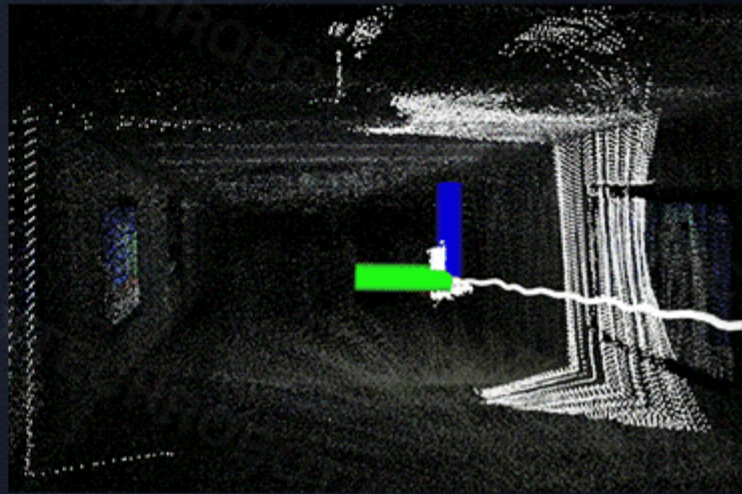
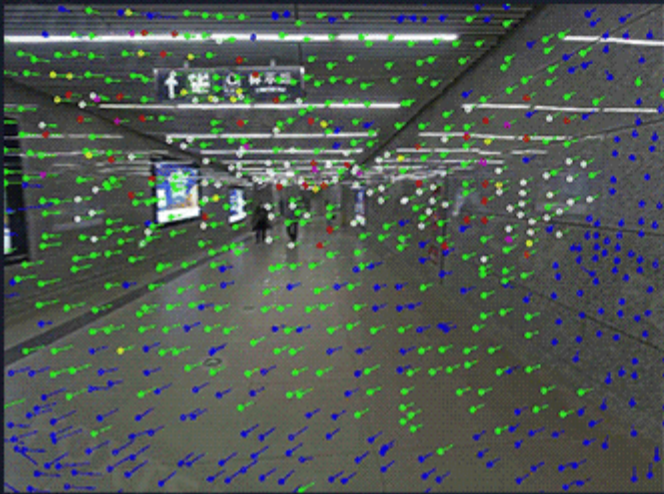


## Texture camera

- 12 megapixels and a field of view of 210°
- It is specially optimized for surveying and mapping applications, making the colored point cloud clearer and more delicate.

## Visual SLAM Algorithms

Fusion of visual SLAM enhances scene adaptability and improves data quality. For scenes with weak structural textures such as subway tunnels, it is impossible to use laser SLAM alone for mapping. Visual SLAM technology can be used for mapping and effectively control the accuracy of the results.



## Abundant extension

SLAM2000 can be expanded to connect to a variety of external devices such as RTK, power supply, tripod, etc.



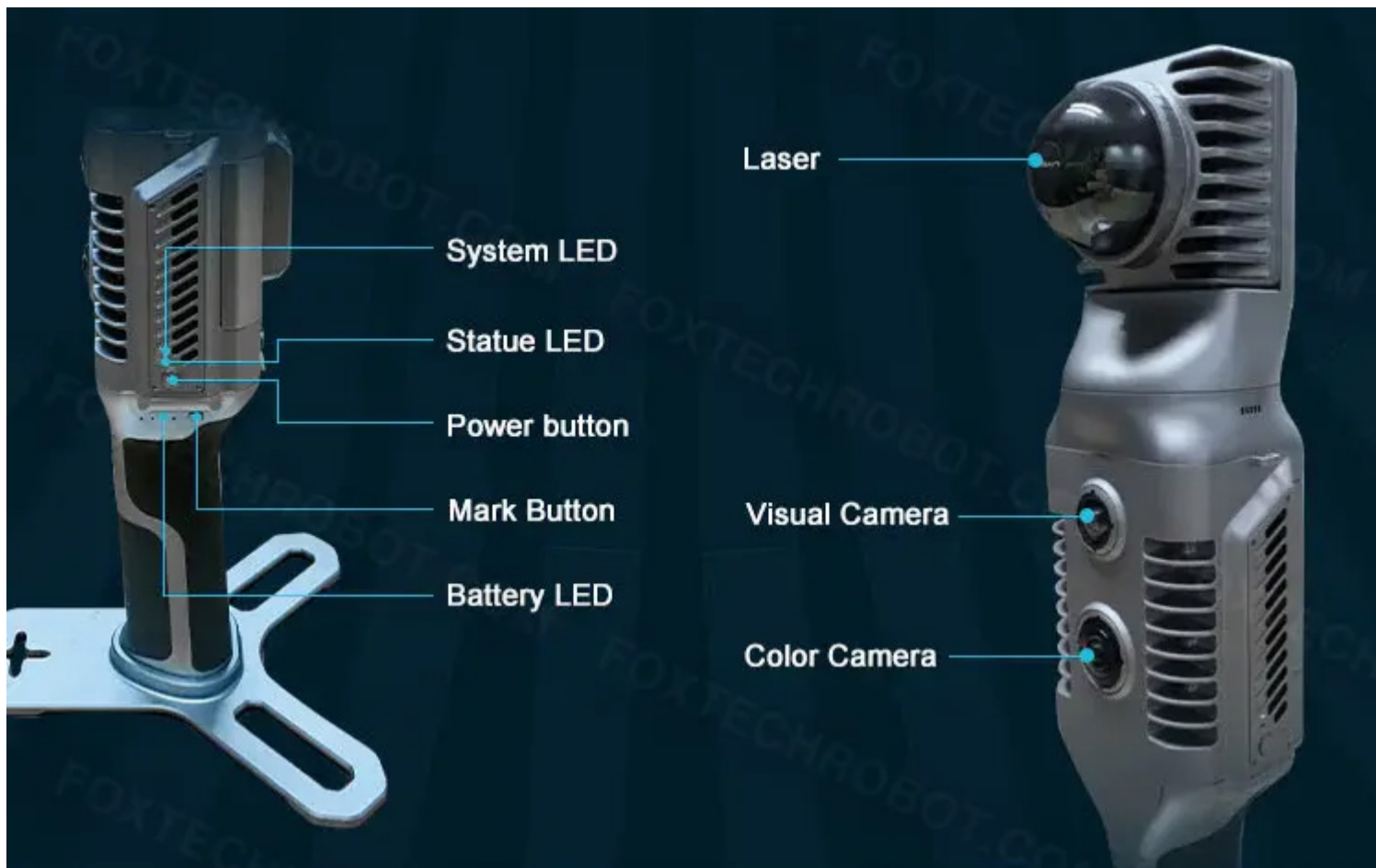
## SLAM GO POST PRO

SLAM GO POST Pro is a PC software that is compatible with SLAM2000. The software can perform one-click SLAM mapping, coordinate conversion, point cloud coloring, etc., and can support point cloud browsing, editing, data roaming, measurement and other functions.

## SLAM GO

Slam2000 can be widely used in closed spaces, volumetric surveying and mapping, emergency rescue, real-time navigation and other scenarios.





## Application

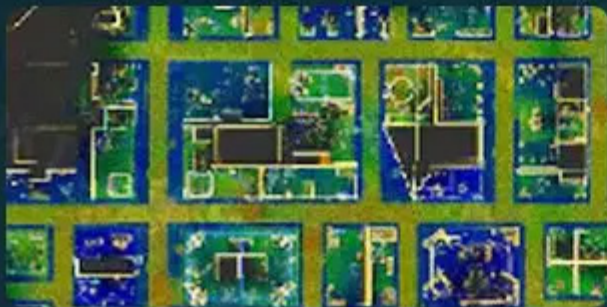
Slam2000 can be widely used in closed spaces, volumetric surveying and mapping, emergency rescue, real-time navigation and other scenarios.



Stairs



Underground Parking



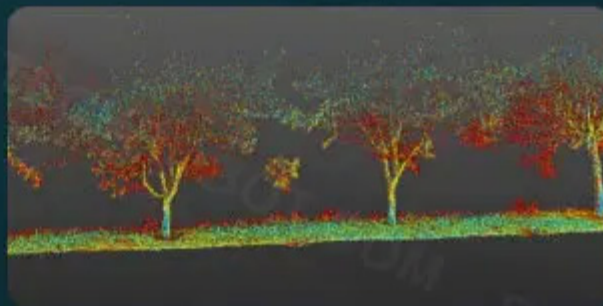
Indoor



Building



Relic History



Gardening

# Product Package List



RTK Mount



Base



Lithium Battery Handle



Aviation Electrical  
Cable



Type-c Charging Cable



Charger



RTK Mounting  
Screws x5



Dongle

Main body	
Weight	925 g (Host) 1450g (With handle and base)
Dimensions	94.5 mm x 84.6mm x 219mm ( Host) 170mm X 173.8mm X 364.5mm (With handle and base)
Power consumption	20W (Typical)
Input voltage	20V
Internal storage	512 GB SSD
Working temperature	—20°C ~ 50°C ( Operation ) , -40°C ~ 70°C ( Storage A10)
Humidity	<95%
Protection class	IP54
Scanning FOV	Panoramic360°
Accuracy	
Point cloud thickness	≤1cm ( Post-processing ) , ≤2 cm ( Realtime )
Relative accuracy	≤1cm ( Post-processing ) , ≤2 cm ( Realtime ) *
Absolute accuracy	≤ 5cm( Post-processing)
Laser scanner	
wavelength	905nm
Laser class	class 1
Range	0.1 m - 70 m @ 80%
FOV	360°(H), -7°- 52°(V)
Laser pulse repetition rate	200kHz
Echo	Single(Strongest)
Frame rate	10 Hz (Typical)
Texture camera	
Resolution	12MP
CMOS size	1 inch
FOV	210° (Diagonal)
Frame rate	30 Hz
Visual camera	
Resolution	12MP
CMOS size	1inch
FOV	100° (Diagonal)
Interface	
USB Type-C 1	SSD data copy
USB Type-C 2	Charge by PD power bank, OTG( 5V)
Circular connector	External power supply(20V), External S-RTK
WiFi	Supported
Lithium battery	
Model	SP30
Input voltage	5V -20V
Output voltage	10.8V
Battery Capacity	3000mAh
Weight	400g
Dimensions	85 mm x 60mm x 144.5 mm
Endurance	Approx.95 mins(SLAM2000 only)

\* In Controlled Environment